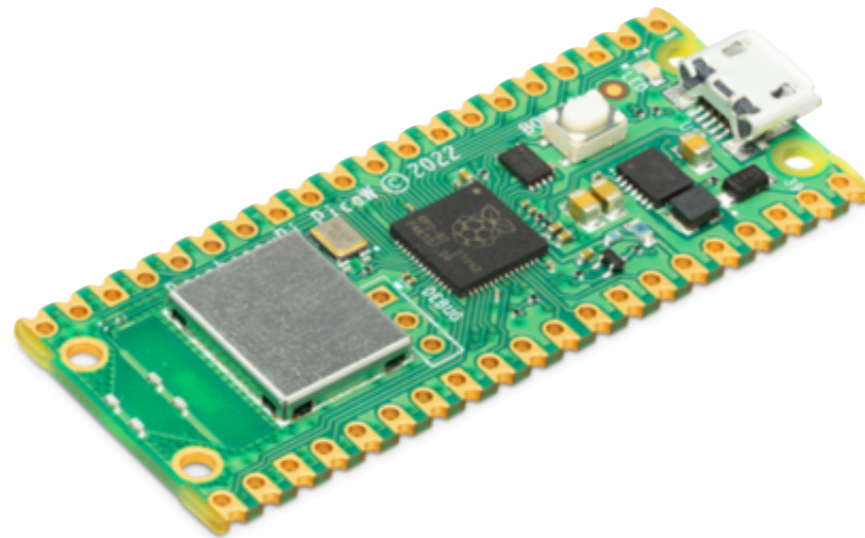




**Jim Kring** 

Presented on May 23, 2023 at

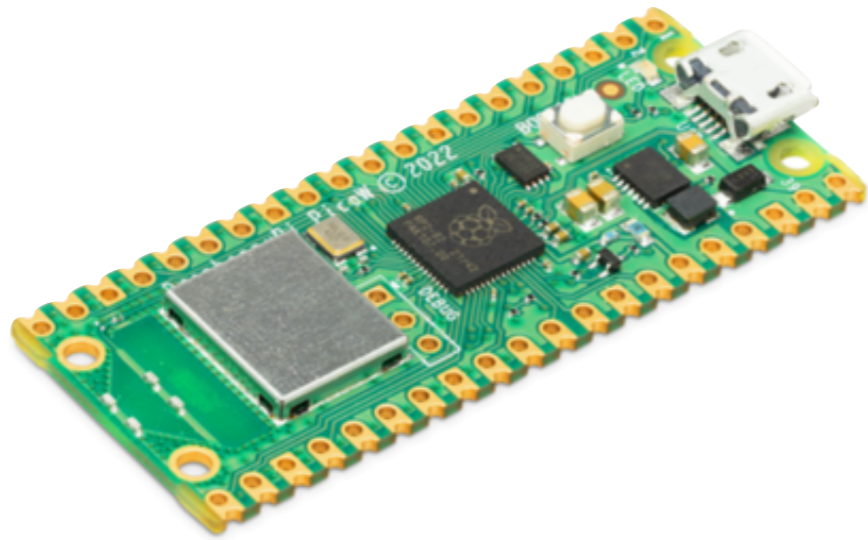


# G Anywhere

Enhancing LabVIEW Development with a  
Cross-Platform Embedded Device Library

**we'll cover these topics**

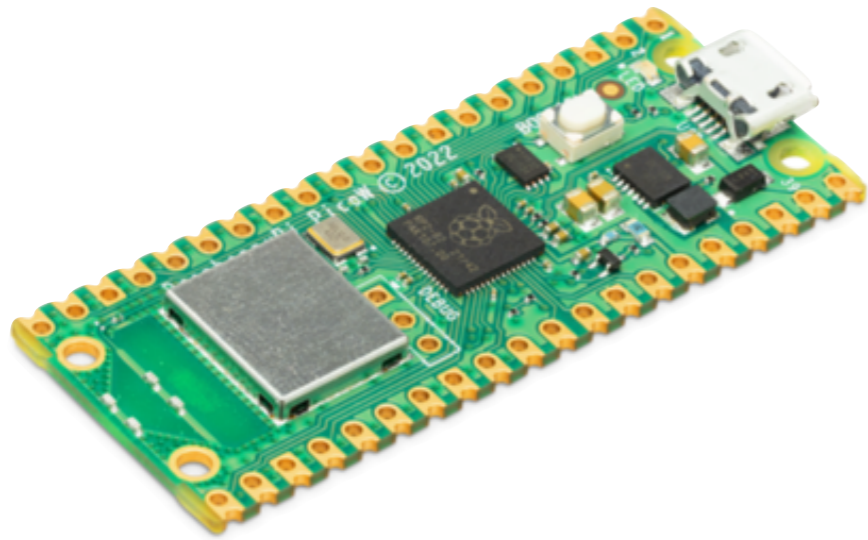
# we'll cover these topics



## **Raspberry Pi Pico**

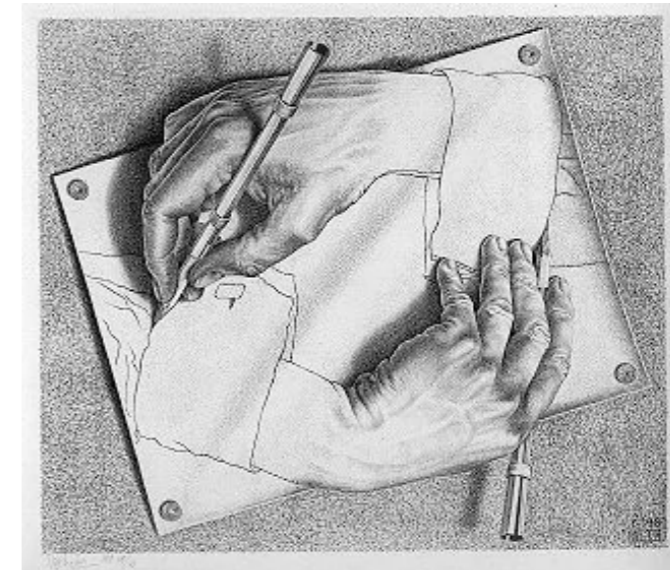
**a great place to run LabVIEW code**

# we'll cover these topics



## Raspberry Pi Pico

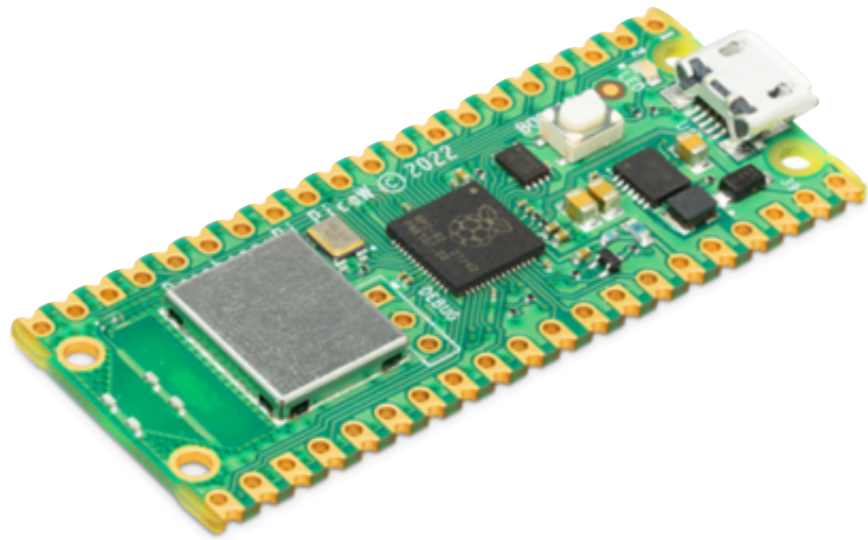
a great place to run LabVIEW code



## Compiling G in G

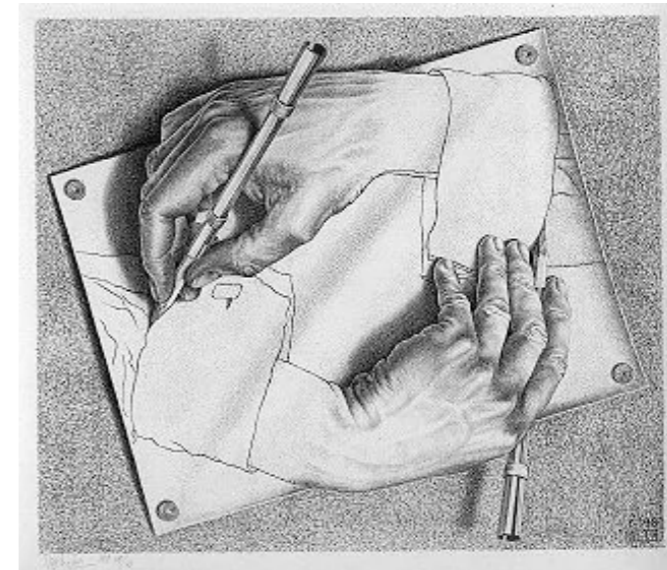
a way to run LabVIEW anywhere

# we'll cover these topics and see some demos!



## Raspberry Pi Pico

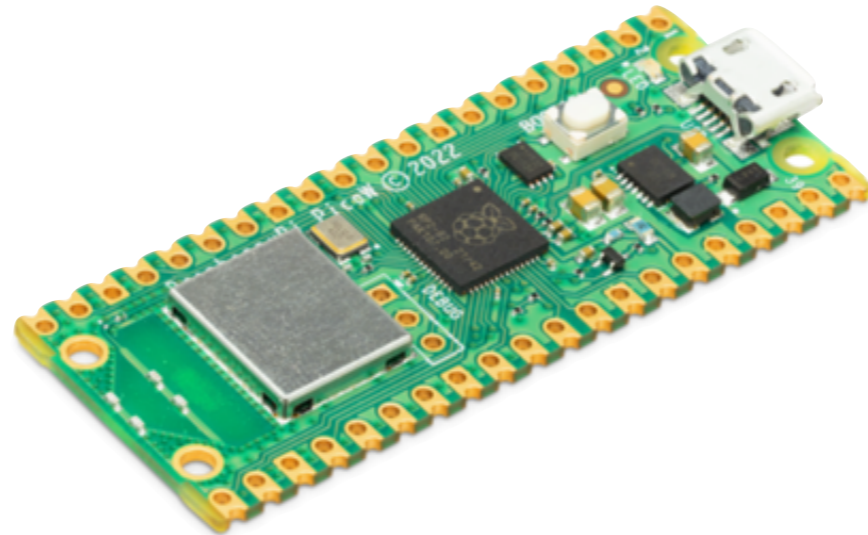
a great place to run LabVIEW code



## Compiling G in G

a way to run LabVIEW anywhere

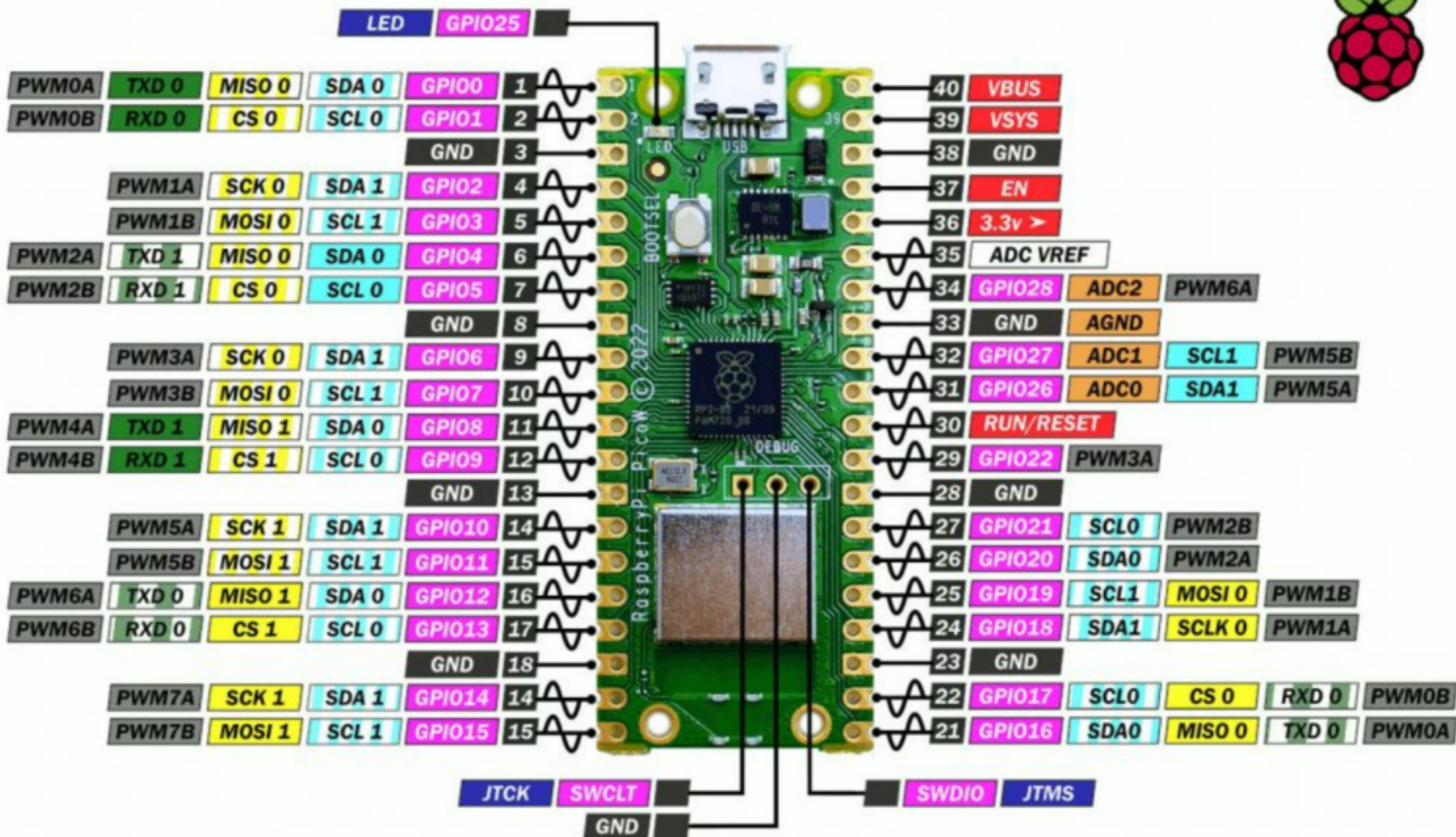
# Raspberry Pi Pico



**a great place to run LabVIEW code**

# Raspberry Pi Pico rp2040

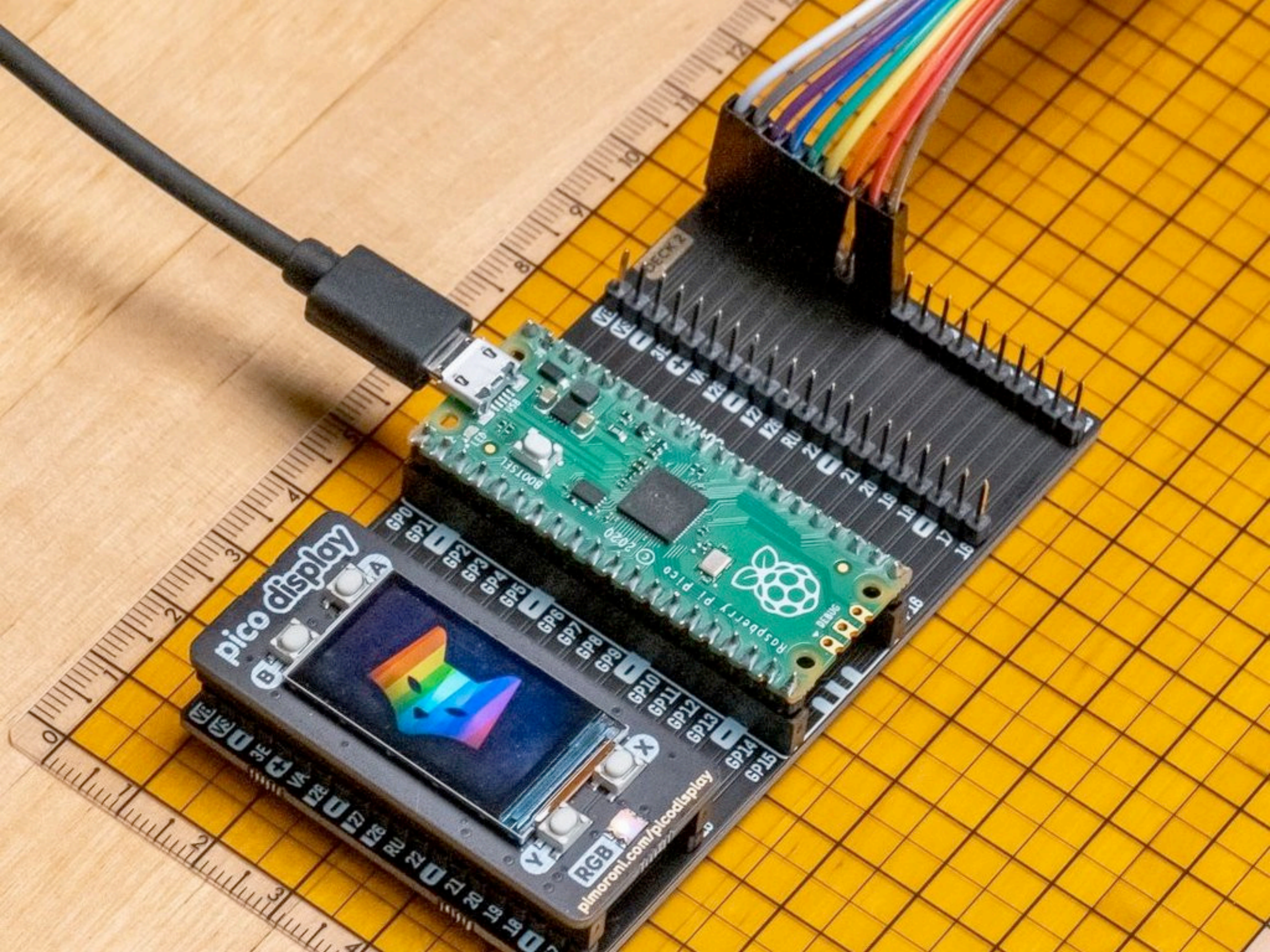
# PINOUT



**Internal board function pins**

- IP Used in ADC mode (ADC3) to measure VSYS/3 **GPI029**
- OP Connected to user LED **GPI025**
- IP VBUS sense - high if VBUS is present, else low **GPI024**
- OP Controls the on-board SMPS Power Save pin **GPI023**



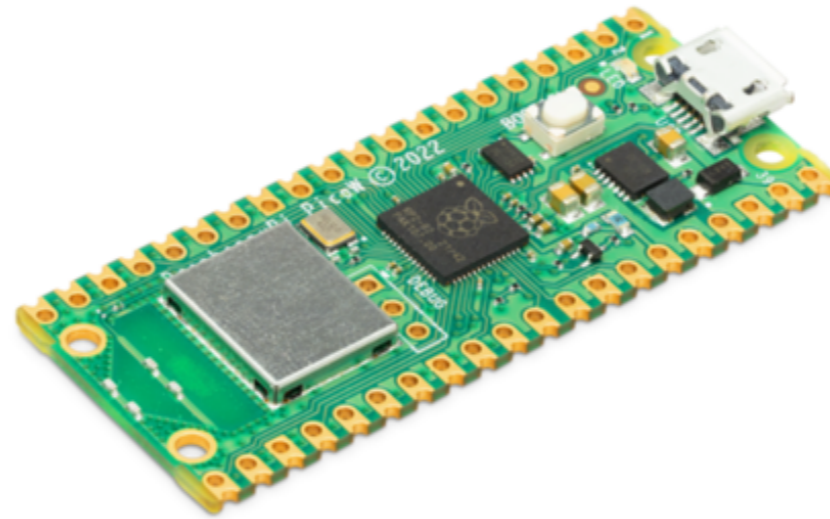






2-Channel RS232 Module for Raspberry Pi Pico, SP3232EEN Transceiver, UART To RS232

**\$8.95**



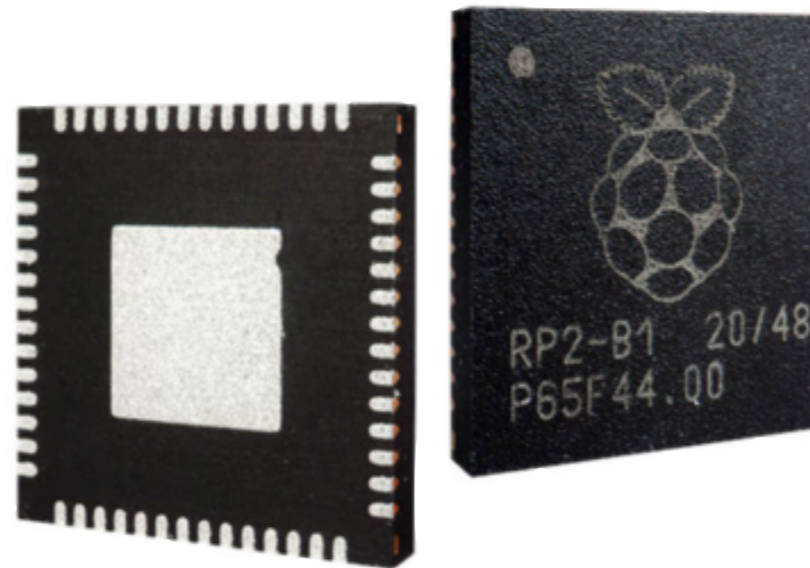
Raspberry Pi Pico W

**\$6.00**



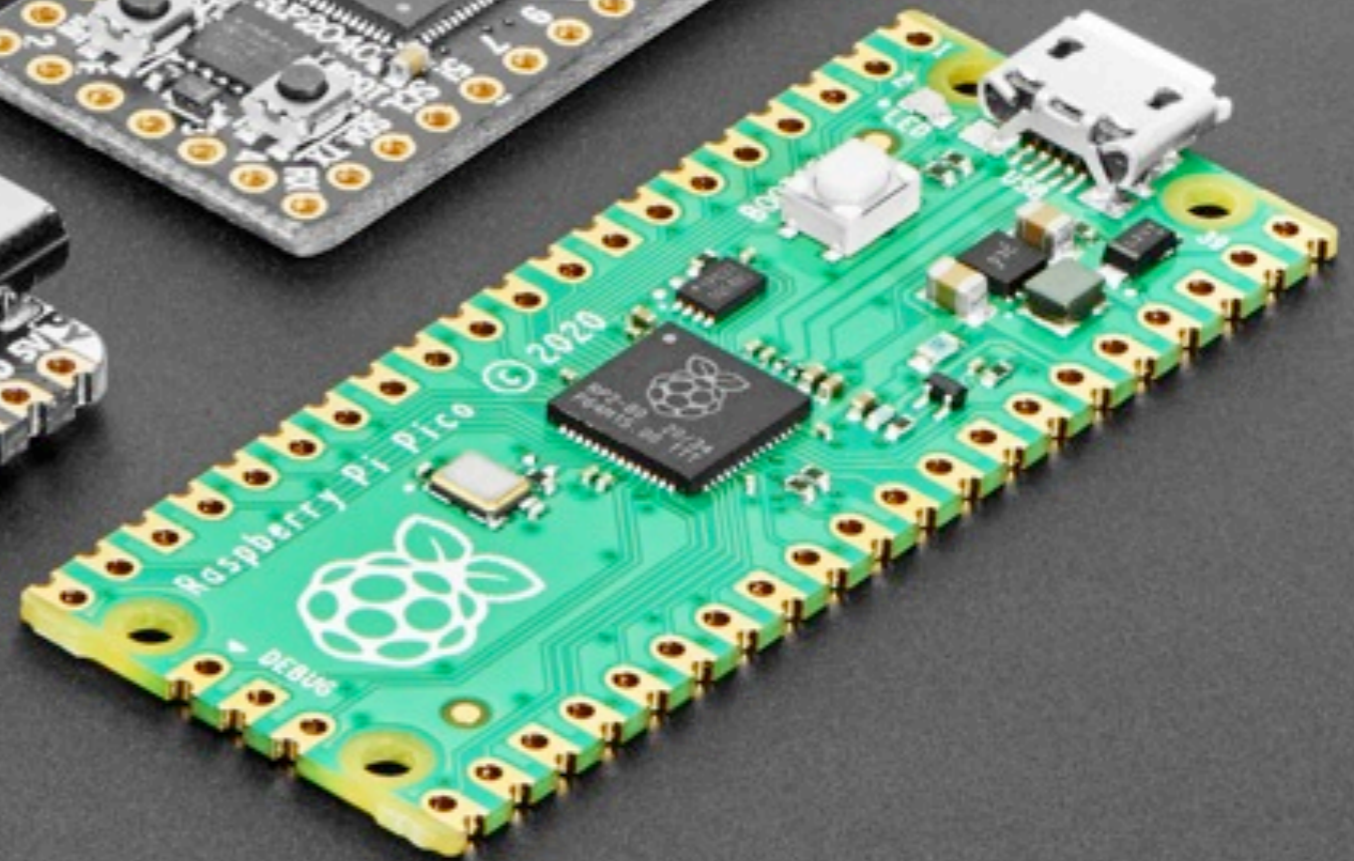
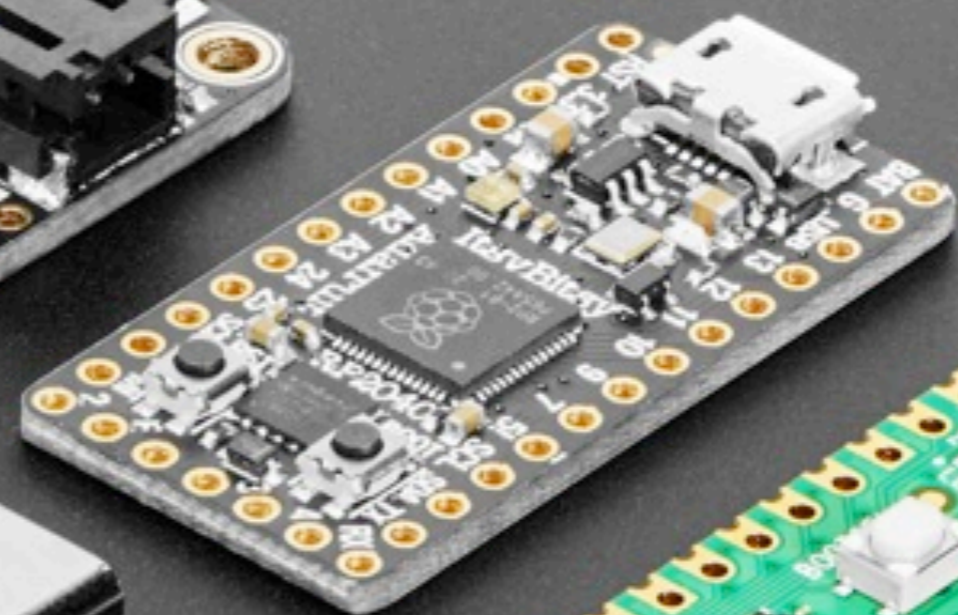
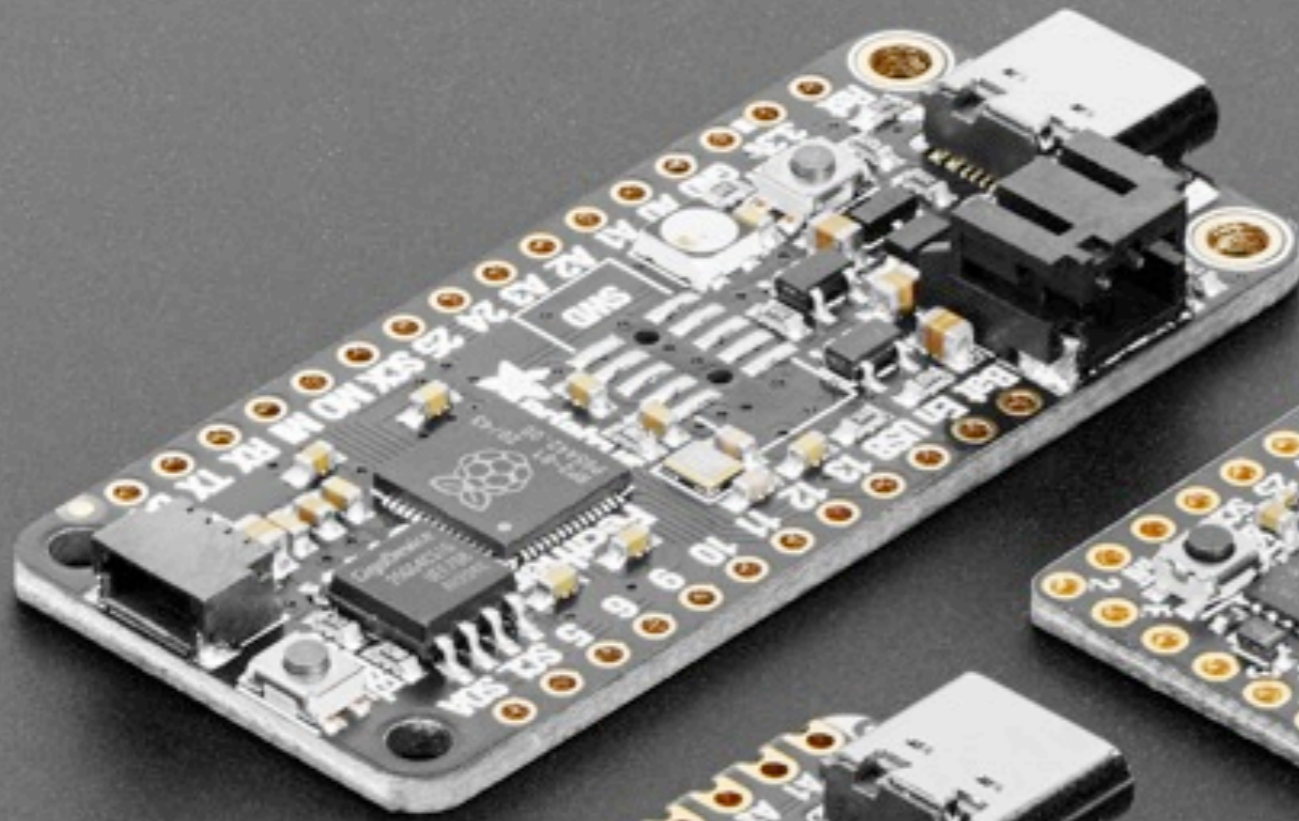
CAN Bus Module for Raspberry Pi Pico, UART to CAN conversion

**\$24.95**



Raspberry Pi RP2040

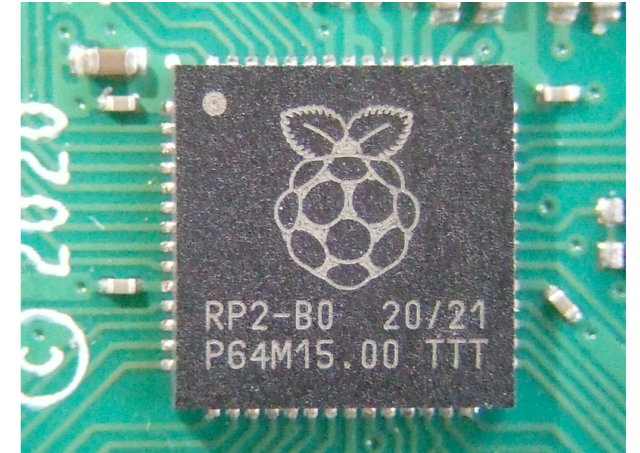
**\$1.00**





RP2-B0 20/21  
P64M15.00 TTT

# RP2040 $\mu$ C



- Dual-core Arm Cortex-M0+ processor, flexible clock up to 133 MHz
- **264kB on-chip SRAM**
- 2 × UART, 2 × SPI controllers, 2 × I2C controllers, 16 × PWM channels
- 1 × USB 1.1 controller and PHY, with host and device support
- 8 × Programmable I/O (PIO) state machines for custom peripheral support
- Low-power sleep and dormant modes. Temperature sensor.
- Accelerated integer and floating-point libraries on-chip

**embedded software  
no operating system**



**embedded software**  
**no operating system**

264kB on-chip SRAM



**embedded software**  
**no operating system**

264kB on-chip SRAM





**embedded software  
no operating system**

264kB on-chip SRAM

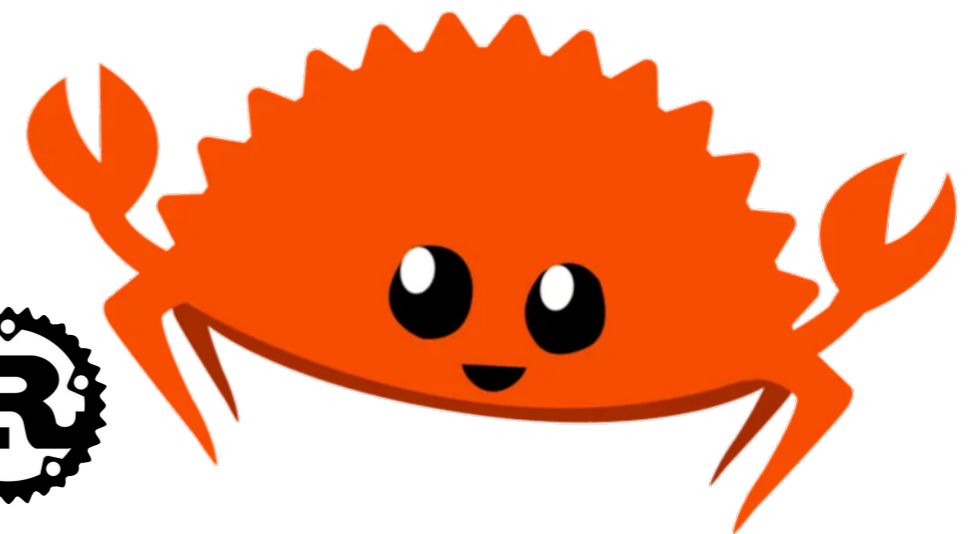






**embedded software  
no operating system**

264kB on-chip SRAM



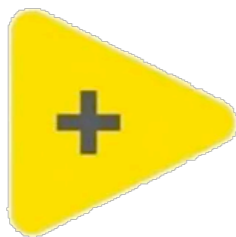


embedded software  
no operating system

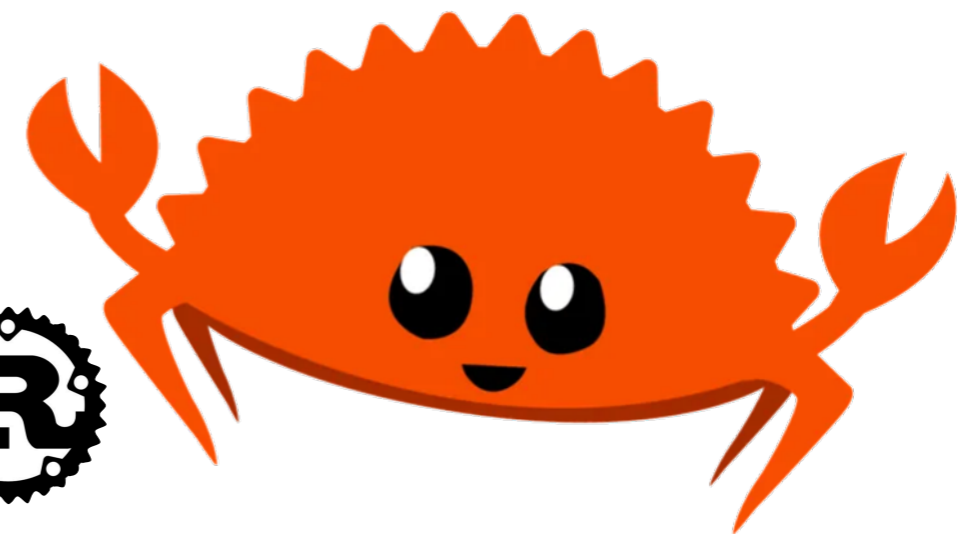
264kB on-chip SRAM

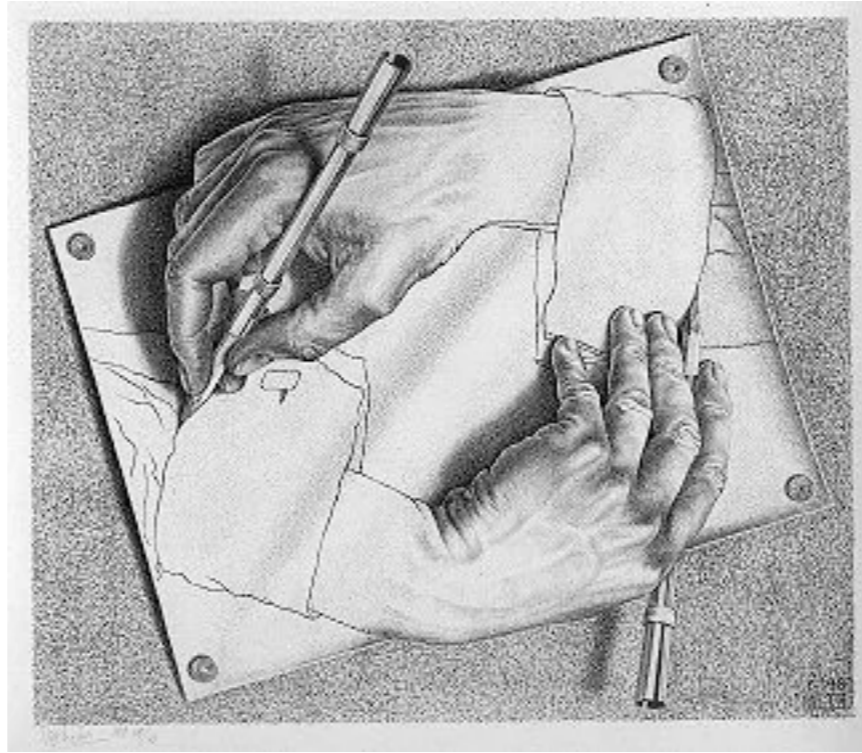


?



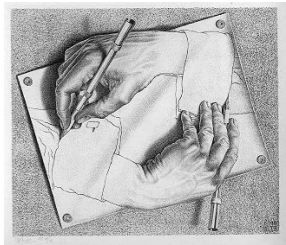
LabVIEW™



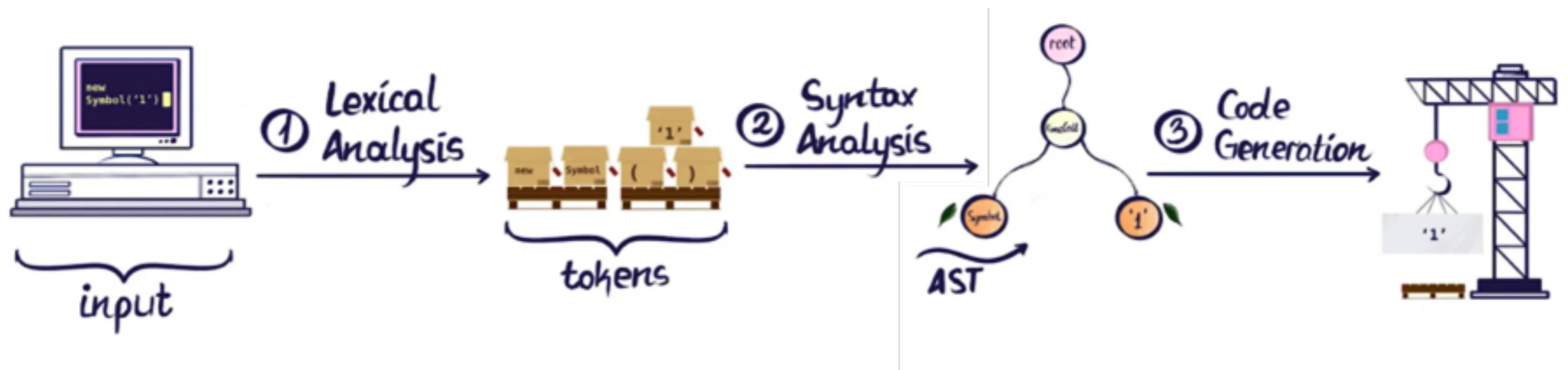


# Compiling G with G

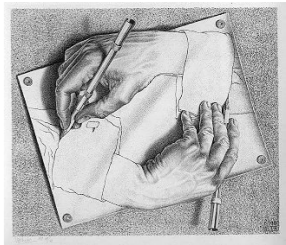
Proving to ourselves that G is a real programming language  
by writing a compiler in G that can compile itself



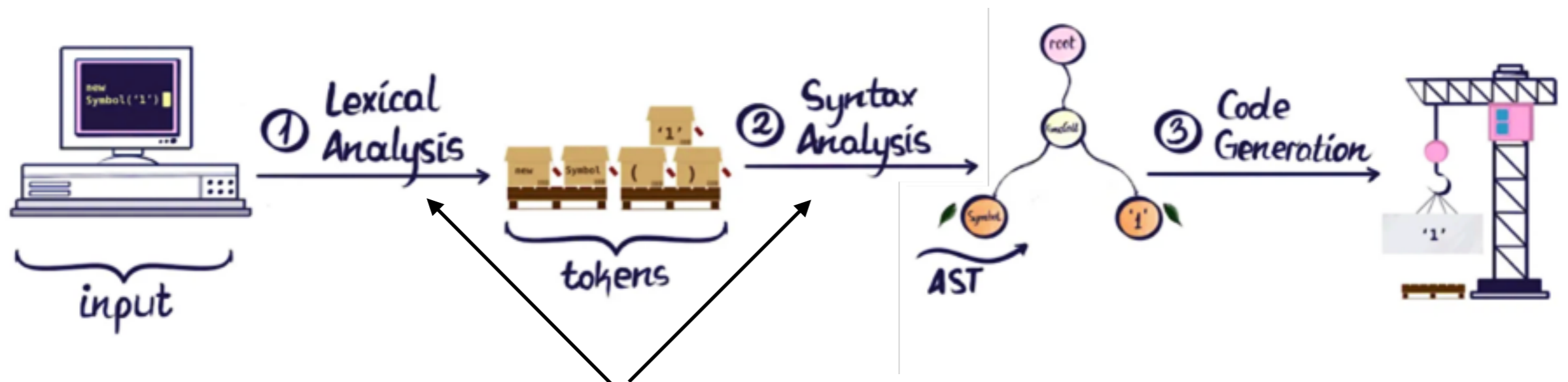
# What a Compiler does



A compiler transforms instructions from a source format to some other target format, so it can be executed by a machine.

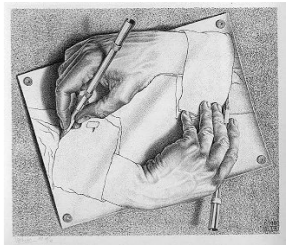


# What a Compiler does

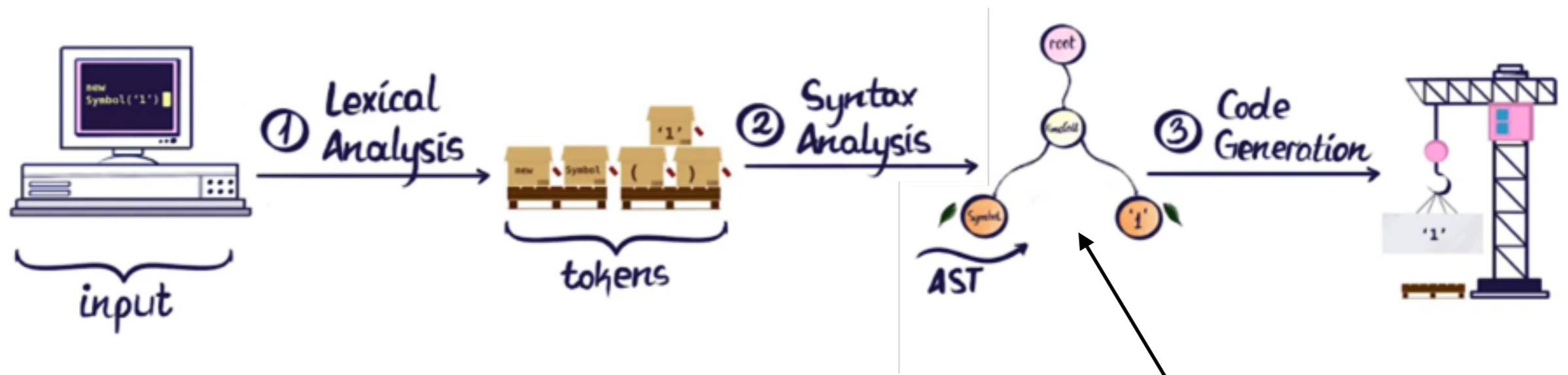


**applicable for text-based languages**

A compiler transforms instructions from a source format to some other target format, so it can be executed by a machine.

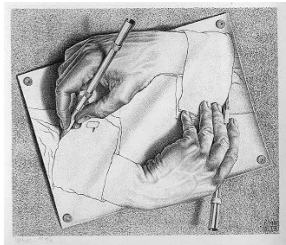


# What a Compiler does

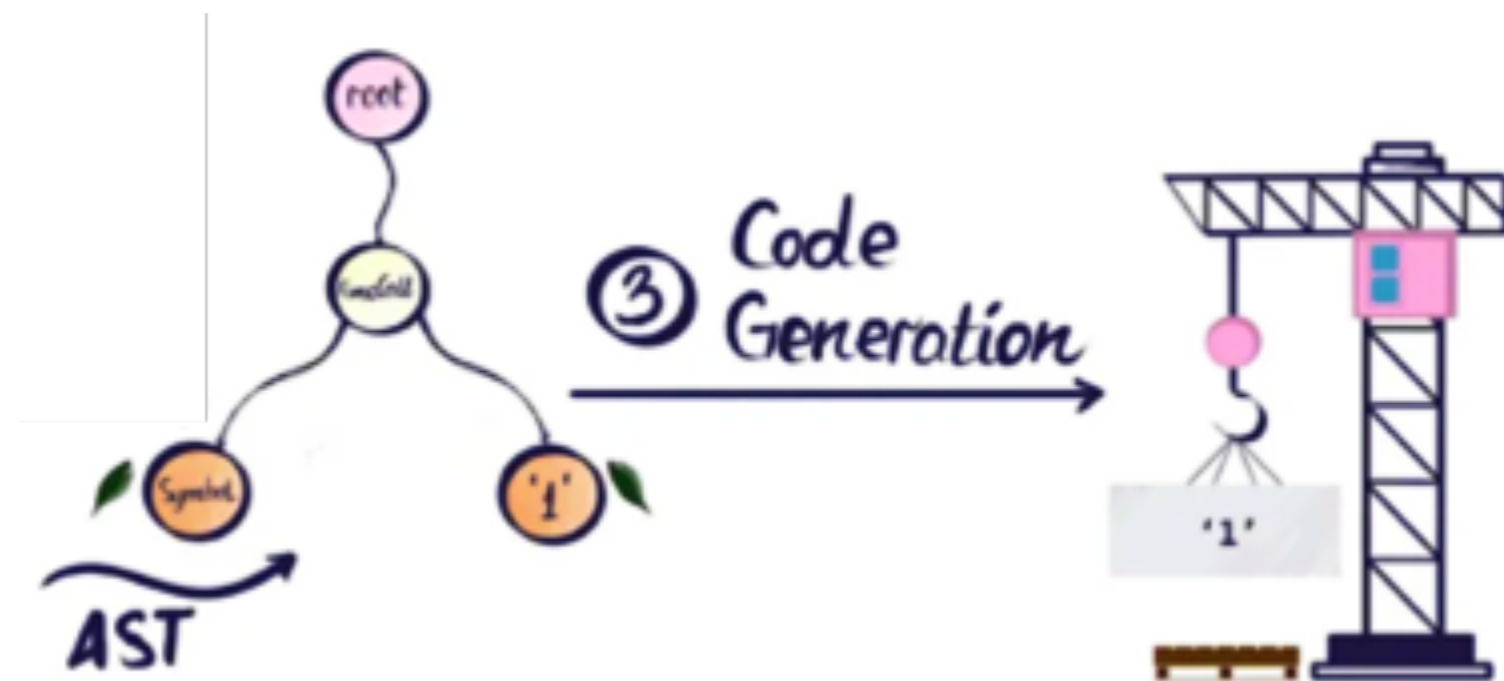


**this looks a lot like a graph  
(nodes and edges)**

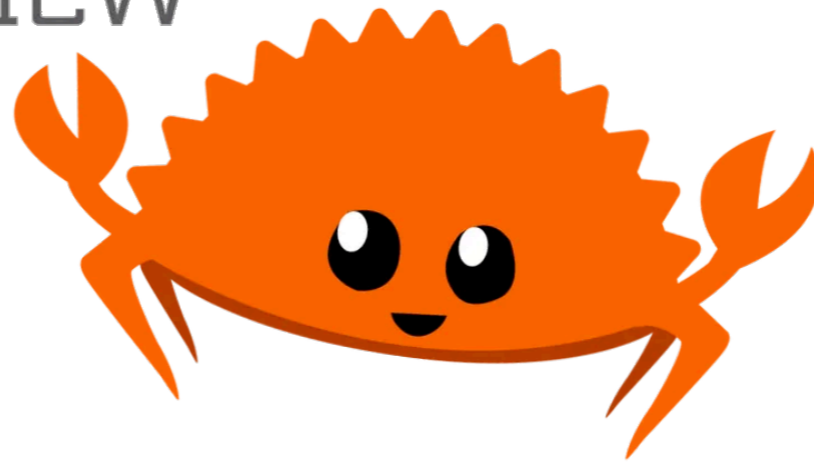
A compiler transforms instructions from a source format to some other target format, so it can be executed by a machine.



# What a G Compiler needs to do



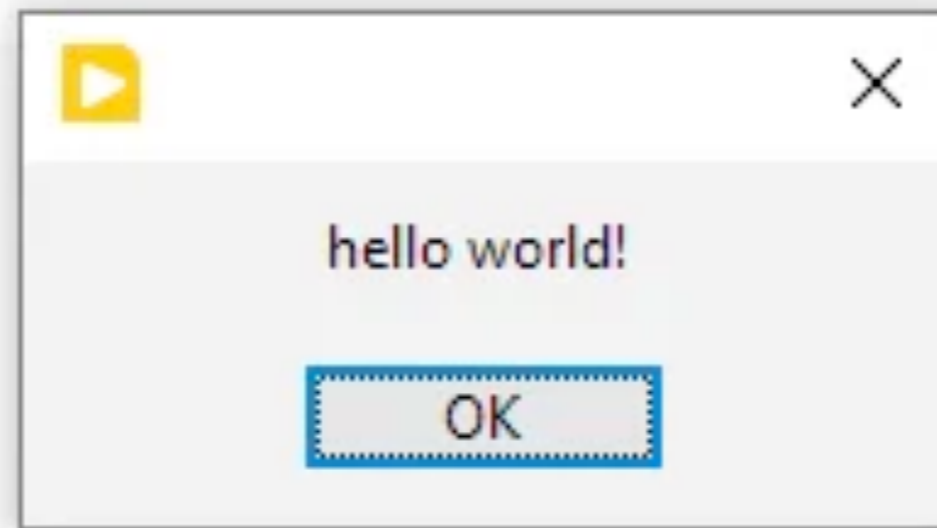
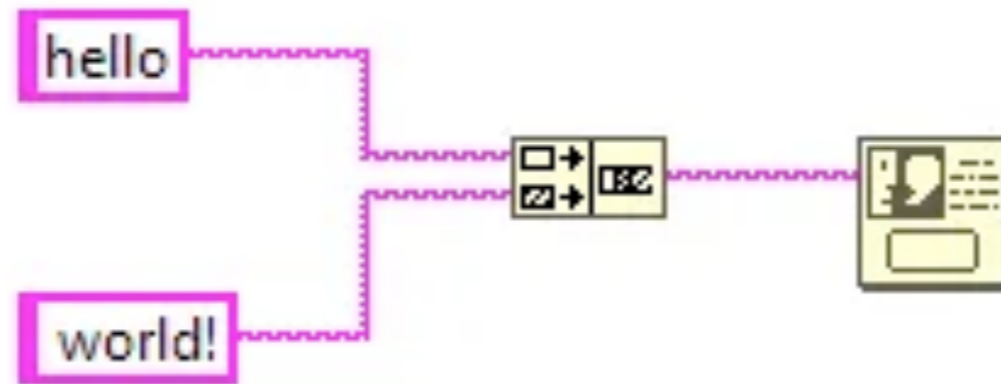
A G compiler needs to generate code from a program's data flow and control flow graphs (DFG and CFG).

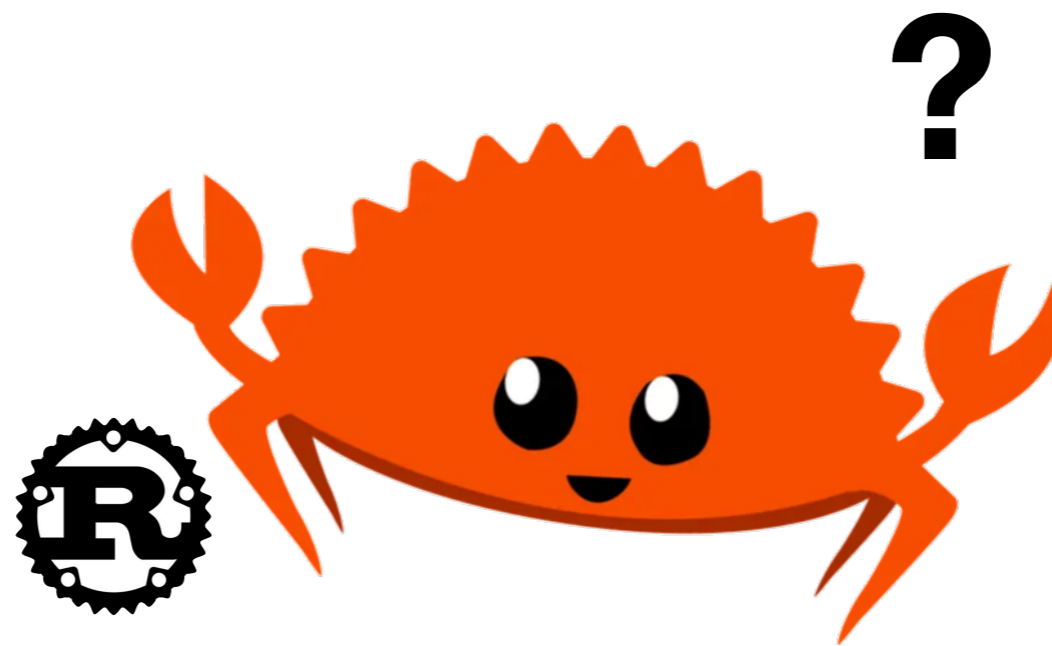
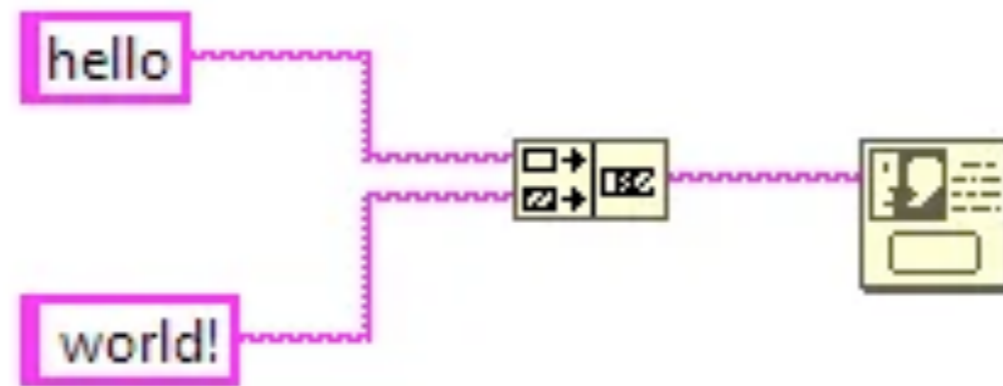


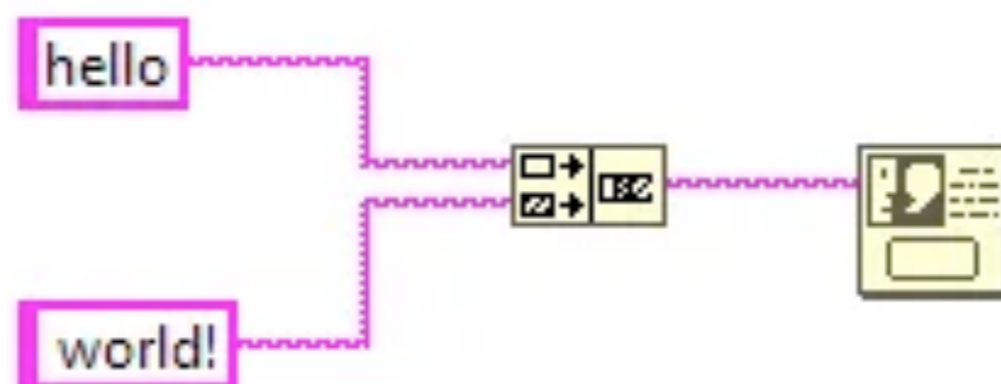
# Translating G to Rust

Mapping G's parallelism to text-based concurrency as an intermediate representation.









```

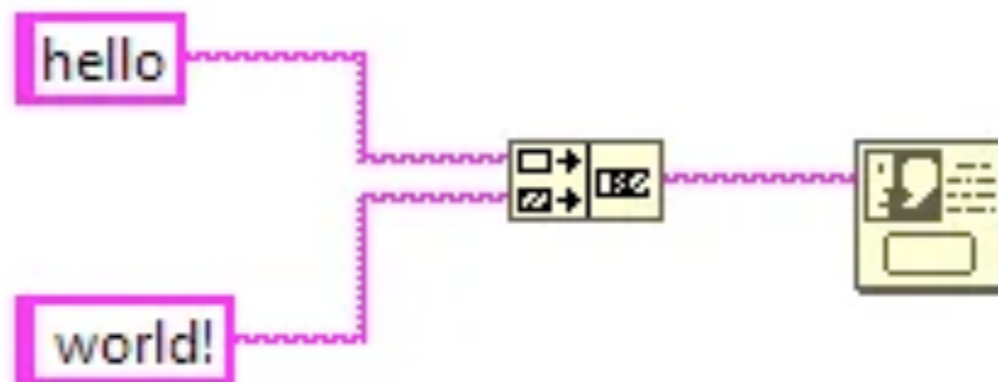
let my_string_01: String = "hello".to_string();

let my_string_02: String = " world!".to_string();

let my_string_03: String = my_concatenate_strings(
    my_string_01, // upper left input wire
    my_string_02 // lower left input wire
);

my_print(
    my_string_03
);

```



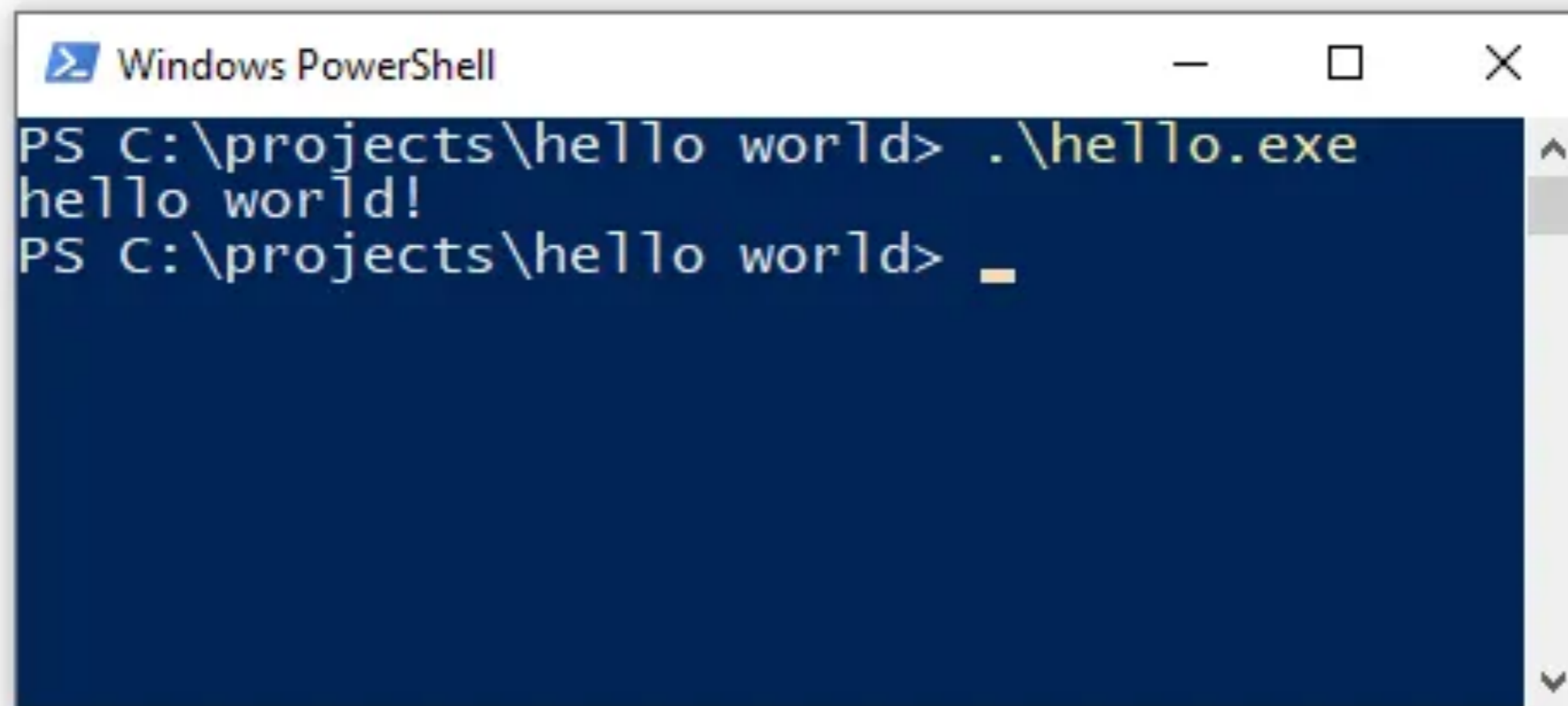
```
let my_string_01: String = "hello".to_string();
```

```
let my_string_03: String = my_concatenate_strings(  
  my_string_01, // upper left input wire  
  my_string_02 // lower left input wire  
);
```

```
my_print(  
  my_string_03  
);
```

```
let my_string_02: String = " world!".to_string();
```

# Demo



```
Windows PowerShell
PS C:\projects\hello world> .\hello.exe
hello world!
PS C:\projects\hello world> _
```

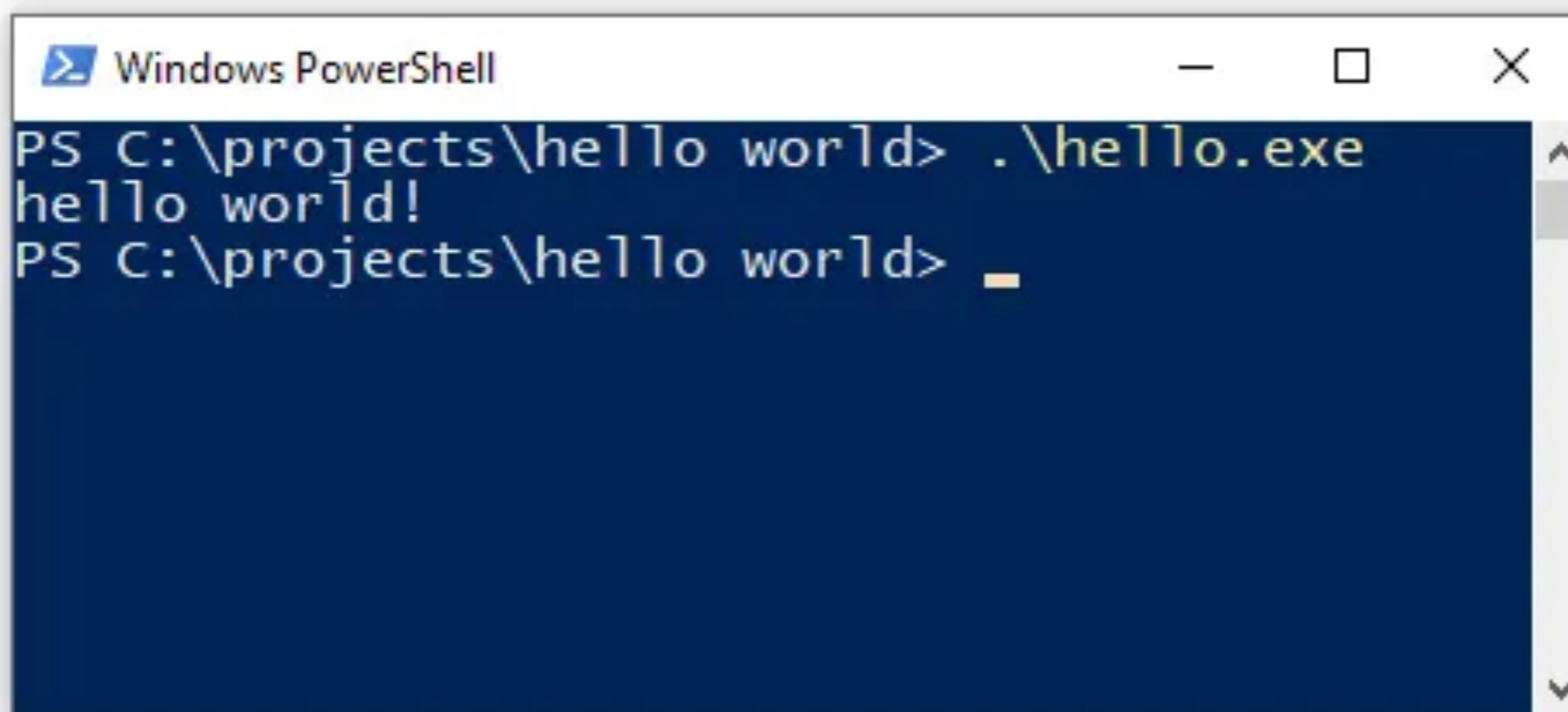
The image shows a screenshot of a Windows PowerShell terminal window. The window title is "Windows PowerShell". The terminal content shows a command prompt at "PS C:\projects\hello world>" where the command ".\hello.exe" has been entered and executed, resulting in the output "hello world!". The prompt is now at "PS C:\projects\hello world> \_".

```
let my_string_01: String = "hello".to_string();
```

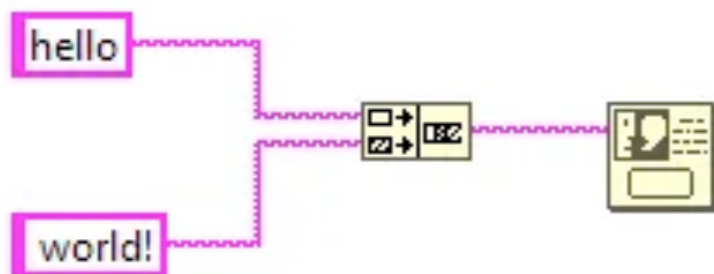
```
let my_string_03: String = my_concatenate_strings(  
  my_string_01, // upper left input wire  
  my_string_02  // lower left input wire  
);
```

```
my_print(  
  my_string_03  
);
```

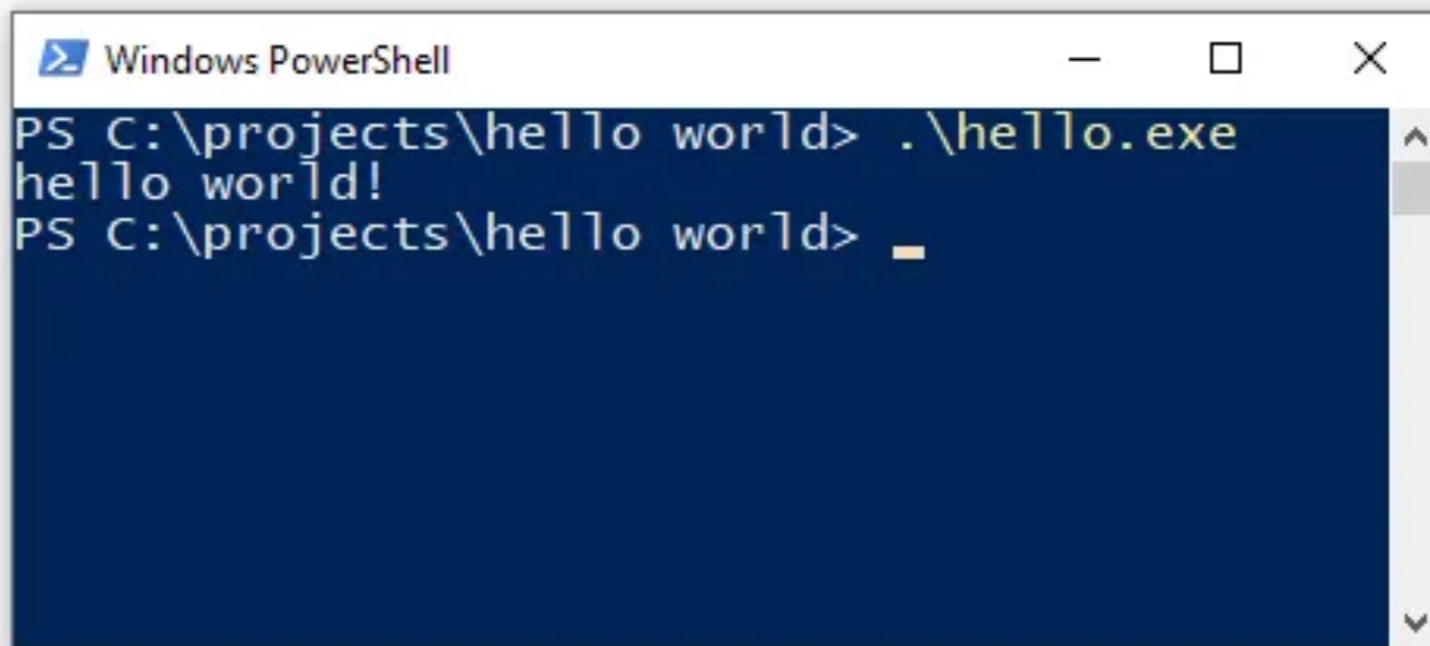
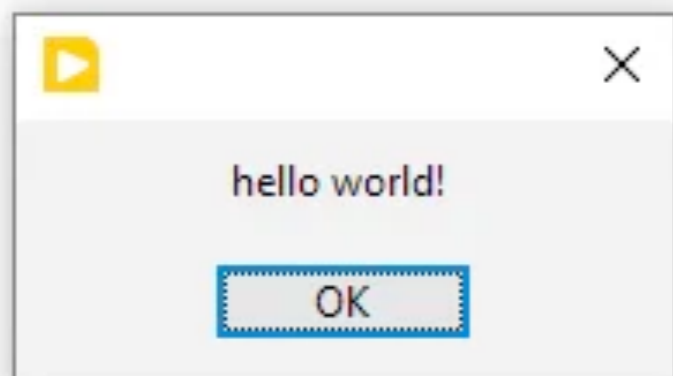
```
let my_string_02: String = " world!".to_string();
```



```
Windows PowerShell  
PS C:\projects\hello world> .\hello.exe  
hello world!  
PS C:\projects\hello world> _
```



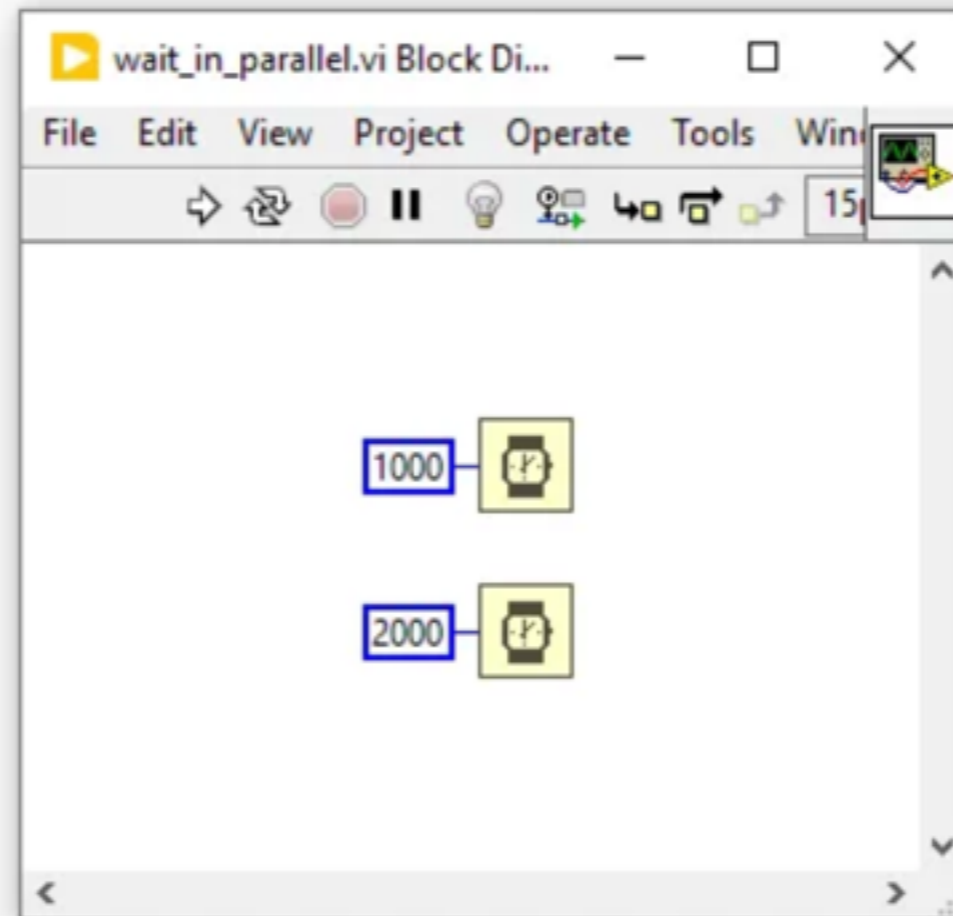
```
let my_string_01: String = "hello".to_string();  
  
let my_string_02: String = " world!".to_string();  
  
let my_string_03: String = my_concatenate_strings(  
    my_string_01, // upper left input wire  
    my_string_02 // lower left input wire  
);  
  
my_print(  
    my_string_03  
);
```



# How about Parallelism?

We need a way to run code asynchronously,  
according to the execution rules of sequential dataflow.





```
// run the first wait  
wait_ms(1000, "Wait 1");  
  
// run the second wait  
wait_ms(2000);  
  
// total wait time = 3000 milliseconds
```

# Text-based Concurrency

We can leverage tools like threads and async features and frameworks of modern languages (like rust).

# Threads

- `thread::spawn` runs a block of code asynchronously.`
- `thread::spawn` returns a thread handle`
- `join` waits until the thread completes and returns its data`
- This is a lot like ACBRN in LabVIEW

```
// the main entry point of our program
fn main() {

    // let's start our stopwatch
    let start_time = Instant::now();

    // run the first wait in its own thread
    let thread_1 = thread::spawn(move || {
        wait_ms(1000, "Wait 1");
    });

    // run the second wait in its own thread
    let thread_2 = thread::spawn(move || {
        wait_ms(2000, "Wait 2");
    });

    // wait until both threads are finished
    thread_1.join().unwrap();
    thread_2.join().unwrap();

    // get the total elapsed time of our program
    let total_duration = start_time.elapsed();

    // display the results
    println!(
        "Total execution time: {:.{:03} seconds",
        total_duration.as_secs(),
        total_duration.subsec_millis()
    );
}
```

# Async & Await

Provides a framework to make “async” and act a little bit like `thread::spawn``.

Requires framework (runtime engine) to execute the async tasks to completion.



**Jim Kring** 

# Next Steps

Visit my blog at <https://create.vi> to stay up to date on progress.  
Please feel free to message me if you are interested in contributing or learning more.  
Find me on LinkedIn —> [@jimkring](#)